

# Statistical Inference in Distributed and Constrained Settings

## Part 2: Unified Lower Bounds

What will we see?

- More general lower bounds that apply to high-dimensional models
- Bounds that allow interaction

The model:

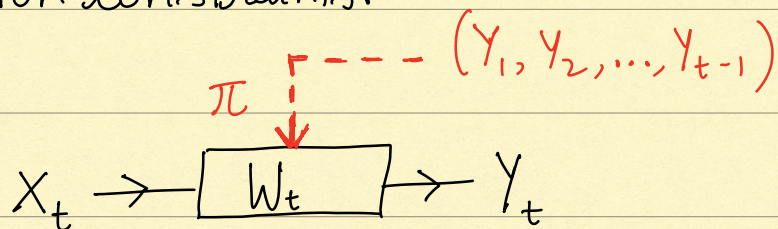
(2)

- $\mathcal{P}(\mathcal{H}) = \{p_\theta, \theta \in \Theta\}$   
a parametric family of distributions on  $\mathcal{X}$
- $X_1, \dots, X_n$   
i.i.d. samples from an *unknown*  
 $p_\theta \in \mathcal{P}(\mathcal{H})$

•  $Y_1, \dots, Y_n$

③

Information constraints:



sequentially interactive

•  $\hat{\Theta}(Y_1, \dots, Y_n)$

Estimate for unknown  $\Theta$

•  $\max_{\Theta \in \mathcal{H}} \mathbb{E}_{\Theta} [\|\Theta - \hat{\Theta}\|_p]$

$\Theta \in \mathcal{H}$

worst-case loss to capture the

performance of your algorithm

estimator  $\hat{\Theta}$  ←

protocol  $\pi$  ←

④

How small can we we make  
 $\max_{\Theta} \mathbb{E}_{\Theta} [\|\theta - \hat{\theta}\|_p]$  if we

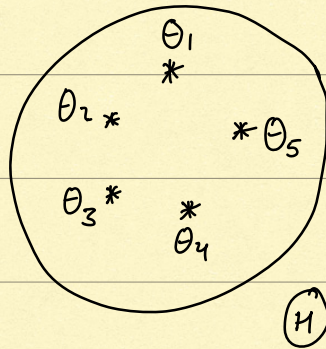
are allowed to use any algorithm  
in the world?

Heuristics from information theory:

- (1) **Uncertainty** about the unknown  $\Theta$   
decreases as we observe  $Y_1, \dots, Y_n$
- (2) This uncertainty can be quantified  
using measures of **information**
- (3) Information is usually **additive** in  $n$
- (4) The presence of  $W_t$ 's will reduce the  
information (**data processing**)

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## (1) Quantifying uncertainty

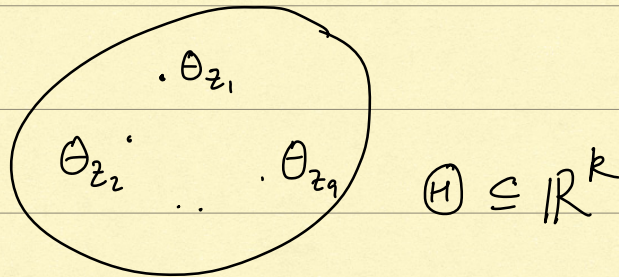


- Choose a finite set of  $M$  points in the parameter space
- Let one of them be chosen randomly and  $n$  samples be generated from it
- Uncertainty remaining upon observing  $Y^n$ 
  - Two points:  $1 - d(P_{\theta_1}^{Y^n}, P_{\theta_2}^{Y^n}) \rightsquigarrow \text{Le Cam}$
  - Multiple points:  $H(Z|Y^n) \rightsquigarrow \text{Fano}$

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→ Average uncertainty for each coordinate  
→ Assouad's method

(Suited for high-dimensional  
+  
interactive)



Embedding:

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$$|\theta_{z,i} - \theta_{z',i}| \approx r \mathbb{1}_{\{z_i \neq z'_i\}}$$

$$\|\theta_z - \theta_{z'}\|^2 \approx r^2 \sum_{i=1}^k \mathbb{1}_{\{z_i \neq z'_i\}}$$

$$\hat{z} = \operatorname{argmin}_{z \in \{-1, 1\}^k} \|\hat{\theta} - \theta_z\|$$

⑧

$$\Rightarrow \mathbb{E}_{\theta_z} \left[ \|\hat{\theta} - \theta_z\|^2 \right]$$

$$\geq \frac{1}{2} \mathbb{E}_{\theta_z} \left[ \|\theta_{\hat{z}} - \theta_z\|^2 \right]$$

$$\approx r^2 \sum_{i=1}^k \mathbb{P}_{\theta_z} [z_i \neq \hat{z}_i]$$

For  $Z \sim \text{unif} \{-1, 1\}^k$ , <sup>Recall:</sup>  $(z \rightarrow \theta_z \rightarrow Y^n \rightarrow \hat{\theta} \rightarrow \hat{z})$

$$\mathbb{E}_Z \left[ \mathbb{E}_{\theta_z} \left[ \|\hat{\theta} - \theta_z\|^2 \right] \right]$$

⑨

$$\geq r^2 \sum_{i=1}^k \mathbb{P}[z_i \neq \hat{z}_i]$$

$P(Z_i \neq \hat{Z}_i) \rightsquigarrow$  probability of error  
for a binary  
hypothesis testing prob.

$$P_{+i}^{y^n} = p(Y^n | Z_i = +1)$$

$$P_{-i}^{y^n} = p(Y^n | Z_i = -1)$$

$$P(Z_i \neq \hat{Z}_i) \geq \frac{1}{2} (1 - d(P_{+i}^{y^n}, P_{-i}^{y^n}))$$

$$\mathbb{E}_Z \left[ \mathbb{E}_{\theta_2} [\|\hat{\theta} - \theta_2\|^2] \right] \quad (10)$$

$$\gtrsim r^2 \sum_{i=1}^k (1 - d(P_{+i}^{y^n}, P_{-i}^{y^n}))$$

Thus,

loss  $\geq$  "uncertainty"

$$\approx r^2 k \left( 1 - \frac{1}{k} \sum_{i=1}^k d(P_{+i}^{y^n}, P_{-i}^{y^n}) \right)$$

## (2) Uncertainty to information

(11)

$$\left( \frac{1}{k} \sum_{i=1}^k d(p_{+i}^{y^n}, p_{-i}^{y^n}) \right)^2 \leq \frac{1}{k} \sum_{i=1}^k d(p_{+i}^{y^n}, p_{-i}^{y^n})^2$$

Lemma.  $p_+, p_-$  two distributions on  $\mathcal{X}$

$$U \sim \text{unif} \{-1, +1\}$$

$$P_{X|U=+1} = p_+$$

$$P_{X|U=-1} = p_-$$

Then,

$$d(p_+, p_-)^2 \leq 2I(U \wedge X)$$

Proof.  $d(p_+, p_-)^2 \leq 2(d(p_+, q)^2 + d(p_-, q)^2)$

$q = \frac{p_+ + p_-}{2}$

$$\leq D(p_+ \| q) + D(p_- \| q) = 2I(U \wedge X) \quad \blacksquare$$



(12)

Lemma  $\Rightarrow$

$$d(p_{+i}^{Y^n}, p_{-i}^{Y^n})^2 \leq 2 I(Z_i \wedge Y^n)$$

=

$$\leq 2 I(Z_i \wedge Y^n, Z^{-i})$$

(independence of  $Z_1, \dots, Z_k$ )

$$\leq 2 I(Z_i \wedge Y^n | Z^{-i})$$

$$\left( \frac{1}{k} \sum_{i=1}^k d(p_{+i}^{Y^n}, p_{-i}^{Y^n}) \right)^2$$
$$\leq \frac{1}{k} \sum_{i=1}^k I(Z_i \wedge Y^n | Z^{-i}).$$

(13)

(1), (2)  $\Rightarrow$

$$\mathbb{E}_Z[\mathbb{E}_{p_{\theta_2}}[\|\theta_2 - \hat{\theta}\|^2]] \quad \text{"loss"}$$
$$\approx r^2 k \left( 1 - \sqrt{\frac{2}{k} \sum_{i=1}^k \mathbb{I}(Z_i \wedge Y^n | Z^{-i})} \right)$$

$\swarrow$  "information"

need to derive an upper bound for this information quantity

(3) Tensorization of information

(14)

$$\mathbb{I}(Z_i \wedge Y^n | Z^{-i}) = \sum_{t=1}^n \mathbb{I}(Z_i \wedge Y_t | Z^{-i}, Y^{t-1})$$

(4) How  $W_t$ 's reduce information

$$\text{Bounding } I(Z_i \wedge Y_t | Z^{-i} = z^{-i}, y^{t-1} = y^{t-1})$$

Simplifying notation:

(15)

$$W_t = W^{y^{t-1}}$$

$$z^{+i} = (z_1, \dots, z_{i-1}, 1, z_{i+1}, \dots, z_k)$$

$$z^{-i} = (z_1, \dots, z_{i-1}, -1, z_{i+1}, \dots, z_k)$$

$$P_{z^{+i}}^{W_t} = p(Y_t | Z_i = 1, z^{-i}, y^{t-1})$$

$$X_t \sim P_{z^{+i}} \rightarrow \boxed{W_t} \rightarrow Y_t$$

$$P_{z^{-i}}^{W_t} = p(Y_t | Z_i = -1, z^{-i}, y^{t-1})$$

$$X_t \sim P_{z^{-i}} \rightarrow \boxed{W_t} \rightarrow Y_t$$

$$I(Z_i \wedge Y_t | Z^{-i} = z^{-i}, y^{t-1} = y^{t-1})$$

(16)

$$= \frac{1}{2} D\left(P_{z^{+i}}^{W_t} \parallel \frac{1}{2} P_{z^{+i}}^{W_t} + \frac{1}{2} P_{z^{-i}}^{W_t}\right)$$

$$+ \frac{1}{2} D\left(P_{z^{-i}}^{W_t} \parallel \frac{1}{2} P_{z^{+i}}^{W_t} + \frac{1}{2} P_{z^{-i}}^{W_t}\right)$$

Conditioning on  $Z^{-i}$  helped - with this  
 the distribution of  $X_t$  doesn't depend on  $y^{t-1}$ :

$$X_t = (Z_i, Z^{-i}) - y^{t-1}$$

$$\Rightarrow I(Z_i \wedge Y_t | Z^{i-1}, y^{t-1})$$

$$= \mathbb{E}_Z \left[ \mathbb{E}_{y^{t-1}} \left[ D(P_Z^{W_t} \parallel \frac{1}{2} P_Z^{W_t} + \frac{1}{2} P_{Z^{\oplus i}}^{W_t}) \right] \right]$$

•  $p, q$  two distributions on  $\mathcal{X}$  (17)

•  $W: \mathcal{X} \rightarrow \mathcal{Y}$

$$D(p^W \parallel \frac{1}{2} p^W + \frac{1}{2} q^W)$$

$$\leq d_{\chi^2} \left( p^W \parallel \frac{1}{2} p^W + \frac{1}{2} q^W \right)$$

$$= \int \frac{\left( \frac{1}{2} p^W(y) - \frac{1}{2} q^W(y) \right)^2}{\frac{1}{2} (p^W(y) + q^W(y))} du$$

$$\leq \frac{1}{2} \int \frac{(p^w(y) - q^w(y))^2}{p^w(y)} d\mu$$

$$p^w(y) - q^w(y) = \mathbb{E}_p [W(y|X) \underbrace{\left(\frac{q(x)}{p(x)} - 1\right)}_{=: \phi(x)}]$$

$$= \frac{1}{2} \int \frac{[\mathbb{E}_p [W(y|X) \phi(x)]]^2}{[\mathbb{E}_p [W(y|X)]]} d\mu$$

(18)

$$D(p^w \| \frac{1}{2} p^w + \frac{1}{2} q^w) \leq$$

$$\frac{1}{2} \int \frac{[\mathbb{E}_p [\phi(x) W(y|X)]]^2}{[\mathbb{E}_p [W(y|X)]]} d\mu$$

where  $\phi(x) = \frac{q(x)}{p(x)} - 1$ .

$$\Rightarrow \sum_{i=1}^k \sum_{t=1}^n I(z_i \wedge y_t | z^{-i}, y^{t-1}) \quad (19)$$

$$= \sum_{i=1}^k \sum_{t=1}^n \mathbb{E}_{z, y^{t-1}} \left[ D \left( P_z^{W_t} \parallel \frac{1}{2} P_z^{W_t} + \frac{1}{2} P_{z^{\oplus i}}^{W_t} \right) \right]$$

$$\leq \frac{1}{2} \int \frac{\mathbb{E}_{P_z} [\phi_{z,i}(x) W_t(y|x)]^2}{\mathbb{E}_{P_z} [W_t(y|x)]} d\mu$$

where  $\phi_{z,i}(x) = \frac{dP_{z^{\oplus i}}}{dP_z}(x) - 1$ .

$$\leq \frac{1}{2} \cdot n \cdot \max_z \max_{W \in \mathcal{W}}$$

$$\sum_{i=1}^k \int \frac{\mathbb{E}_{P_z} [\phi_{z,i}(x) W(y|x)]^2}{\mathbb{E}_{P_z} [W(y|x)]} d\mu$$

(20)

Theorem (Average information contraction bound)

$$|\theta_{z,i} - \theta_{z',i}| \approx r \mathbb{1}_{\{z_i \neq z'_i\}}$$

$$\frac{d p_{z^{\otimes i}}}{d p_z} = 1 + \phi_{z,i}^r$$

$$\mathbb{E}_z \mathbb{E}_{P_{\theta_z}} \left[ \|\theta_z - \hat{\theta}\|_2^2 \right]$$

$$\gtrsim r^2 R \left( 1 - \sqrt{\frac{n}{2} \max_z \max_W \frac{1}{k} \sum_{i=1}^k} \right)$$

$$\int \frac{\mathbb{E}_{P_z} \left[ \phi_{z,i}^r(x) W(y|X) \right]^2}{\mathbb{E}_{P_z} [W(y|X)]} d\mu$$

Further bounds for

(21)

$$\sum_{i=1}^k \frac{\mathbb{E}_{P_Z} [W(y|X) \phi_{z,i}(x)]^2}{\mathbb{E}_{P_Z} [W(y|X)]}$$

Additional conditions:

(22)

- $\mathbb{E}_Z [\phi_{z,i}^2] \leq \alpha^2$

- $\phi_{z,1}, \dots, \phi_{z,k}$  are orthogonal

Then, since  $\phi_{z,i}$  are zero-mean under  $P_Z$ ,

$$\sum_{i=1}^k \mathbb{E}_{P_Z} [a(x) \phi_{z,i}(x)]^2 = \sum_{i=1}^k \langle a, \phi_{z,i} \rangle^2$$

$$\stackrel{?}{=} \sum_{i=1}^k \langle a - \mathbb{E}[a], \phi_{z,i} \rangle^2 \stackrel{?}{\leq} \|a - \mathbb{E}[a]\|^2$$



$$\Rightarrow \sum_{i=1}^k \frac{\mathbb{E}_{P_z} [W(y|X) \phi_{z,i}]^2}{\mathbb{E}_{P_z} [W(y|X)]} \leq \frac{\text{Var}_{P_z} (W(y|X))}{\mathbb{E}_{P_z} [W(y|X)]}$$

Additional conditions:

(23)

- $\mathbb{E}_z [\phi_{z,i}^2] \leq \alpha^2$

- $\phi_{z,1}, \dots, \phi_{z,k}$  are independent and  $\sigma^2$ -subgaussian under  $P_z$

Under these assumptions, Gibbs variational formula can be used to show that

$$\begin{aligned} & \sum_{i=1}^k \frac{\mathbb{E}_{P_z} [\phi_{z,i}(X) W(y|X)]^2}{\mathbb{E}_{P_z} [W(y|X)]} \\ & \leq 2\alpha^2 \sigma^2 \mathbb{E}_{P_z} \left[ W(y|X) \ln \frac{W(y|X)}{\mathbb{E}_{P_z} [W(y|X)]} \right] \end{aligned}$$

$$\mathbb{E}_{P_z} [W(y|X)]$$

$$\Rightarrow \frac{\sum_{i=1}^k \int \mathbb{E}_{P_z} [\phi_{z,i}(x) W(y|X)]^2 d\mu}{\mathbb{E}_{P_z} [W(y|X)]} \leq 2\alpha^2 \sigma^2 I(P_z; W)$$

Summary:

(24)

$$\mathbb{E}_Z \mathbb{E}_{P_{\theta_z}} [\|\theta_z - \hat{\theta}\|_2^2]$$

$$\geq r^2 k \left( 1 - \sqrt{\frac{n}{2} \max_z \max_W \frac{1}{k} \sum_{i=1}^k \int \frac{\mathbb{E}_{P_z} [\phi_{z,i}^r(x) W(y|X)]^2 d\mu}{\mathbb{E}_{P_z} [W(y|X)]}} \right)$$

Assumptions:

(i)  $\mathbb{E} [\phi_{z,i}^r]^2 \leq \alpha^2$

(ii)  $\phi_{z,1}, \dots, \phi_{z,k}$  orthonormal

(iii)  $\phi_{z,1}, \dots, \phi_{z,k}$  independent and  $\sigma^2$ -subgaussian

(25)

$$(i), (ii) \Rightarrow \geq r^2 k \left( 1 - \sqrt{n\alpha^2 \max (\text{Var}_{P_z} (W(y|X)))_{d\mu}} \right)$$

$$1 - \sqrt{2k} \max_{z, W} \frac{\mathbb{E} p_z[W(y|X)]}{\mathbb{E} p_z[W(y|X)]}$$

$$(i), (iii) \Rightarrow \geq r^2 k \left( 1 - \sqrt{\frac{n\alpha^2}{2k} \max_{z, W} I(p_z; W)} \right)$$

So far we have made heuristics (1), (2), (3) concrete

(4) Information reduces due to  $W$

• Communication constraints:

$$I(p_z; W) \leq k \text{ and } \sum_y \frac{\text{Var}(W(y|X))}{\mathbb{E}[W(y|X)]} \leq 2^k$$

• Privacy constraints:  $\sum_y \frac{\text{Var}(W(y|X))}{\mathbb{E}[W(y|X)]} \leq (e^k - 1)^2$

References and related work:

(26)

Our presentation was based on:

"Unified lower bounds for interactive high-dimensional estimation under information constraints", Acharya, Canonne, Sun, and T.

Strong data processing approach:

- Zhang, Duchi, Jordan, Wainwright, 2013
- Xu and Raginsky, 2017
- Braverman, Gang, Ma, Woodruff, 2016

Remarks:

- (i) Works only for the high-dimensional setting; may not work for discrete dist.
- (ii) Can be recovered from the general bound we presented

## Fisher information based approach:

(27)

- Barnes, Chen, Ozgur 2020
- Barnes, Han, Ozgur 2019, 2020.

### Remarks:

- (1) Works only for  $l_2$  loss
- (2) Can be recovered from the general bound when:

$$\phi_{z,i}^r(x) \approx r \tilde{\phi}_{z,i}^r(x)$$

with

$$\|\tilde{\phi}_{z,i}^r(x)\|_2 \leq \text{constant}$$

for all  $r$  small

(Basically

$$\lim_{r \rightarrow 0} \sum_{i=1}^K \int \frac{\mathbb{E}_{P_z} [\tilde{\phi}_{z,i}^r(x) W(y|x)]^2}{\mathbb{E}_{P_z} [W(y|x)]} d\mu$$

$$\approx \text{Tr} (J^W(\theta))$$

"Trace of the Fisher Info. Matrix"

(28)

Lots of other works:

Similar to what we presented:

- "Geometric lower bounds for distributed parameter estimation under Communication Constraints",  
Ham, Ozgur, Weissman (2020 version).
- Ohad Shamir 2014 also develops a related approach

Extending the Fisher information based approach to a general  $l_p$  loss:

- Sarbu and Zaidi, ISIT 2021

A very different approach: Duchi, Rogers 2019